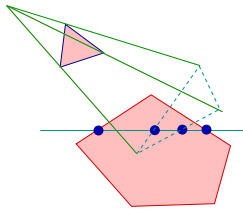


Shadow Generation

$$I_\lambda = k_a I_{a\lambda} O_{a\lambda} + \sum_{i=1}^k S_i f_{att} I_{L_i\lambda} [k_d O_{d\lambda} (\mathbf{N} \cdot \mathbf{L}_i) + k_s (\mathbf{R} \cdot \mathbf{V})^n]$$

$$S_i = \begin{cases} 0 & \text{if light } i \text{ is blocked,} \\ 1 & \text{if light } i \text{ is not blocked.} \end{cases}$$



Scan-line method

- ★ Use light source as the center of projection.
- ★ Project the edges of polygons that cast shadows on the polygons intersecting the scan line.
- ★ Whenever the scan line visits one of the projected points, change the intensity.



Slide 1

Shadow Generation

Two-Pass Object Precision Algorithm:

- ★ Find the portion of each polygon visible from the light source.
- ★ Decompose each polygon into subpolygons, each being either completely lit or completely under dark.
- ★ Render each polygon as follows:
 - If the polygon is in dark, set intensity to the ambient light

$$I_\lambda = k_a I_{a\lambda} O_{a\lambda}.$$
 - If the polygon is lit, then use ambient, diffuse, and specular reflection.
- ★ Repeat the first two steps for each light source.



Slide 2

Shadow Generation

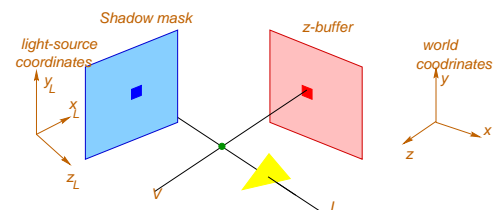
Two-Pass Z-Buffer Algorithm:

- ★ Two passes
 - W.r.t light source
 - W.r.t. view point
- ★ Compute depth information w.r.t. the light source.
light buffer (LB) or shadow mask
- ★ Compute the value of the frame buffer at each pixel π w.r.t. the viewpoint as follows:
 - Suppose the point p in the world coordinate is drawn at pixel π .
 - Determine if p is under shadow.
 - If under shadow, use ambient light.
Otherwise compute the lighting information at π .
- ★ For multiple light sources, maintain a shadow mask for each light source.



Slide 3

Shadow Generation

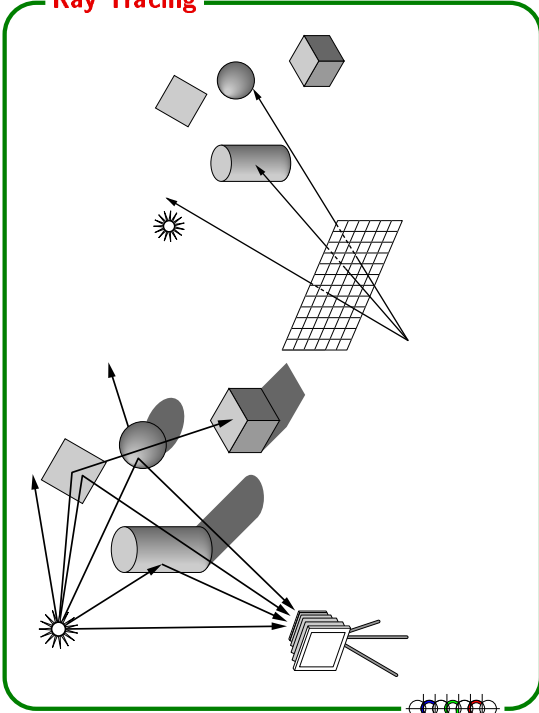


- ★ Compute the pixel (a, b) in the shadow mask corresponding to point p .
- ★ Compute the distance c of p from the light source.
- ★ Compare c with $z_L = LB[a, b]$.
- ★ If $z_L < c$, p is under shadow; otherwise p is lit.



Slide 4

Ray Tracing



Slide 5



Ray Tracing

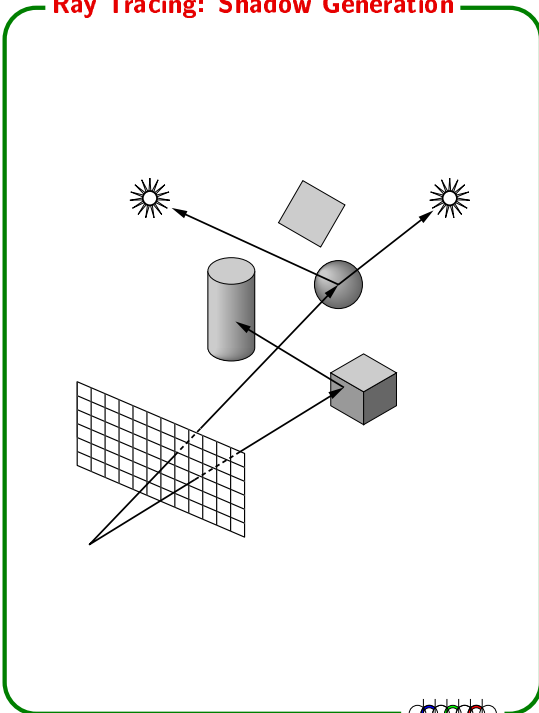
Hidden surface removal

- ★ For each pixel π , shoot a ray ρ from the view point to the center of π .
- ★ If ρ does not intersect any object, color π with the background color.
- ★ Otherwise, compute the first object O intersected by ρ and the first intersection point σ .
- ★ Compute the color at σ using the reflection model.
- ★ Draw π with the computed color.
- ★ Each pixel is colored only once.
- ★ Computing σ is expensive!

Slide 6



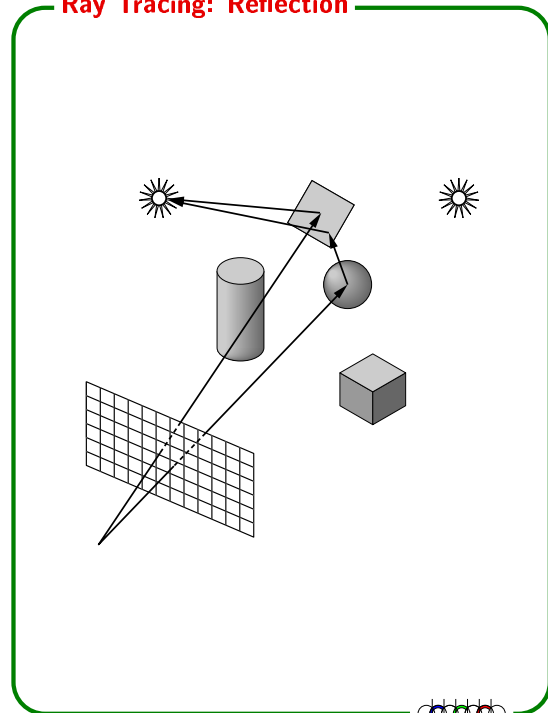
Ray Tracing: Shadow Generation



Slide 7



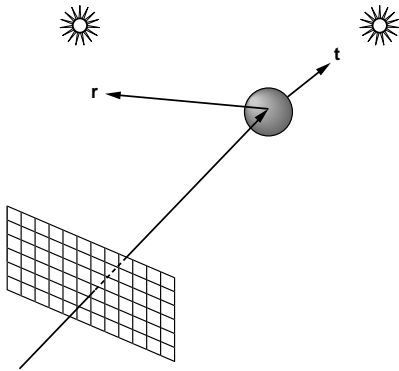
Ray Tracing: Reflection



Slide 8



Ray Tracing: Refraction



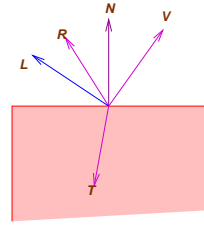
Slide 9

Recursive Ray Tracing

- ★ Extend the standard ray tracing to handle shadows, reflection, and refraction.
- ★ Shoot secondary rays recursively to calculate shadows, reflection, and refraction.

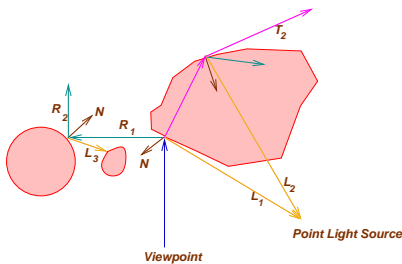
For each pixel π on the screen, do the following:

- ★ **Primary ray (ρ_P):** Ray emanating from the viewer to the center of π .
- ★ If ρ_P doesn't hit any object, render π with the background color.
- ★ Suppose the first intersect point of ρ and an object is p .



Slide 10

Ray Tracing



- ★ Shoot the following **secondary** rays from p :
 - ★ **Shadow ray (ρ_L):** Shoot a ray along $p\vec{L}$.
 - ★ **Reflection ray (ρ_R):** If the object has reflectance property (e.g., mirror), shoot a ray in direction R .
 - ★ **Refraction ray (ρ_T):** If the object is transparent, shoot a ray in direction T .
- ★ If ρ_R, ρ_T hit an object, shoot secondary rays from there as above.
- ★ Apply distance attenuation to the intensity of secondary rays.

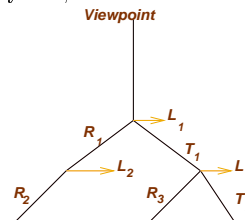
Slide 11

Ray Tracing

Stopping criteria:

- ★ No object is hit.
- ★ Light source is hit.
- ★ Reached a cut-off depth.

Creates a ray tree; evaluate in bottom-up fashion.



$$I_\lambda = k_a I_{a\lambda} O_{a\lambda} + \sum_{i=1}^k S_i f_{att} I_{L_i\lambda} [k_d \cdot O_{d\lambda} (\mathbf{N} \cdot \mathbf{L}_i) + k_s (\mathbf{R} \cdot \mathbf{V})^n] + k_R I_{R\lambda} + k_T I_{T\lambda}$$

Slide 12

Ray Tracing

- ★ Better illumination model.
- ★ Prone to numerical instability.
- ★ Very expensive.

Efficiency Issues:

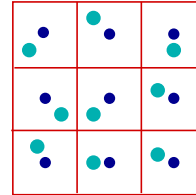
- ★ Ray object intersection: Use object hierarchy, spatial decomposition techniques (oct trees, BSP's).
- ★ Reflection maps
- ★ Adaptive tree depth
- ★ Light buffer



Slide 13

Distributed Ray Tracing

- ★ Handles antialiasing.
- ★ Divide pixel into subpixels.
- ★ Choose pixels at random (under some given distribution).
- ★ Divide each pixel into a grid; *jitter* the centers of the grid randomly within the grid cell.



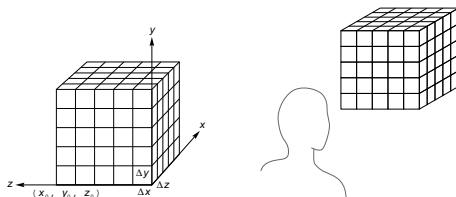
- ★ Instead of uniform sampling, use weighted sampling, e.g., distribution of subpixel depends on light intensity.
- ★ Shoot different rays at slightly different times.



Slide 14

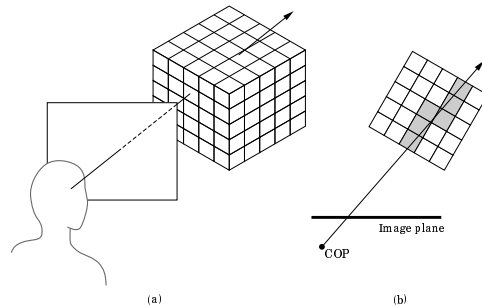
Volume Rendering

- ★ 3D model is constructed a set of small cubes, called *voxels*.
- ★ Each voxel v is assigned a value $f(v)$.
- ★ $f(v)$ determines the color of the voxel.
- ★ Volume data is typically generated in slices and put together.
- ★ Applications
 - Medical imaging
 - Molecular modeling
 - Atmospheric modeling
 - Scientific visualization



Slide 15

Volume Ray Tracing



Repeat the following for each pixel π on the plane

- ★ Draw the ray ρ in the viewing from π
- ★ Find all voxels v_1, v_2, \dots, v_m that intersect ρ
- ★ Assign a weight w_i to each voxel v_i
- ★ Compute the weight sum

$$F(\pi) = \sum_{i=1}^m w_i f(v_i)$$

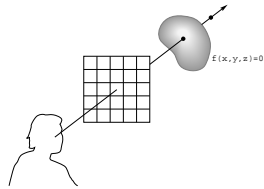


Slide 16

Viewing Implicit Functions

- ★ Regard the scene as a 3-dimensional function
- ★ Each point $(x, y, z) \in \mathbb{R}^3$ has a value $f(x, y, z)$
- ★ Values are sampled at voxel vertices
- ★ Linearly interpolate the values inside a voxel
- ★ For a given $c \in \mathbb{R}$, define

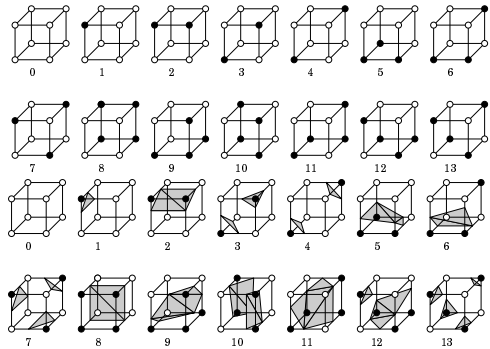
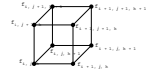
$$\Sigma(c) = \{(x, y, z) \mid f(x, y, z) = c\}$$
- ★ $\Sigma(c)$ is a polyhedral surface
- ★ Render $\Sigma(c)$
- ★ Useful for *gel* like objects.



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Iso-surface Extraction

- $\Sigma(c)$ intersects a voxel if $f(x, y, z) > c$ for some vertices and $< c$ for some others
- ★ Color a vertex z black if $f(x, y, z) > c$ and if $f(x, y, z) < c$
 - ★ Interpolate Σ within a voxel by triangles
 - ★ Visit voxels in a consistent manner, e.g., row by row, then plane by plane.
 - ★ Easy to parallelize; faster than ray tracing.



Slide 18