#### **CS 445**

#### Shortest Paths in Graphs Bellman-Ford Algorithm

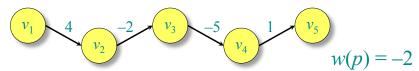
Slides courtesy of Erik Demaine and Carola Wenk

# Paths in graphs

Consider a digraph G = (V, E) with edge-weight function  $w : E \to \mathbb{R}$ . The **weight** of path  $p = v_1 \to v_2 \to \dots \to v_k$  is defined to be

$$w(P) = \sum_{i=2}^{k} w(v_{i-1}, v_i)$$

#### **Example:**



## **Shortest paths**

A *shortest path* from u to v is a path of minimum weight from u to v. The *shortest-path weight* from u to v is defined as

 $\delta(u, v) = \min\{w(p) : p \text{ is a path from } u \text{ to } v\}.$ 

Also called *distance* of *u* from *v* 

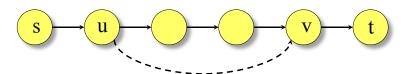
(note – this has nothing to do with the algorithm computing the distance)

Note:  $\delta(u, v) = \infty$  if no path from u to v exists.

## **Optimal substructure**

**Theorem.** A subpath of a shortest path is a shortest path.

*Proof.* Cut and paste:

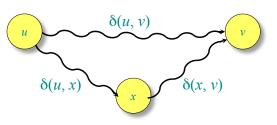


Important: This simple principle will be useful for all the Dynamic programming (and in particular, all Shortest Paths) problems

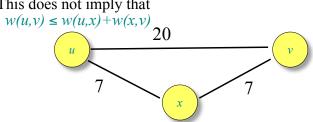
# Triangle inequality

**Theorem.** For all  $u, v, x \in V$ , we have  $\delta(u, v) \le \delta(u, x) + \delta(x, v)$ .

*Proof.* 



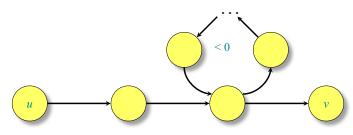
Note: This does not imply that



# Negative-weight cycles

**Recall:** If a graph G = (V, E) contains a negative-weight cycle, then some shortest paths may

#### **Example:**



**Bellman-Ford algorithm:** Finds all shortest-path lengths from a **source**  $s \in V$  to all  $v \in V$ V or determines that a negative-weight cycle exists.

### **Bellman-Ford and Undirected** graphs

Bellman-Ford algorithm is designed for **directed** graphs.

If G is undirected, replace every edge (u,v) with two directed edges (u,v) and (v,u), both with weight w(u,v)

# Bellman-Ford algorithm

$$d[s] \leftarrow 0$$
**for** each  $v \in V - \{s\}$ 

$$do d[v] \leftarrow \infty$$
initialization

for 
$$i \leftarrow 1$$
 to  $|V| - 1$  do  
for each edge  $(u, v) \in E$  do  
if  $d[v] > d[u] + w(u, v)$  then  
 $d[v] \leftarrow d[u] + w(u, v)$   
 $\pi[v] \leftarrow u$ 

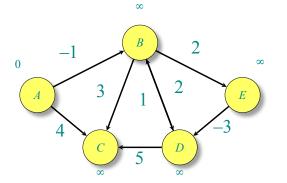
for each edge 
$$(u, v) \in E$$
  
do if  $d[v] > d[u] + w(u, v)$ 

then report that a negative-weight cycle exists

At the end,  $d[v] = \delta(s, v)$ . Time = O(|V||E|).

### **Example of Bellman-Ford**

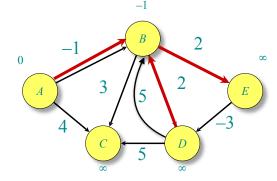
Order of edges: (B,E), (D,B), (B,D), (A,B), (A,C), (D,C), (B,C), (E,D)



A	В	C	D	E
0	∞	∞	$\infty$	$\infty$

### **Example of Bellman-Ford**

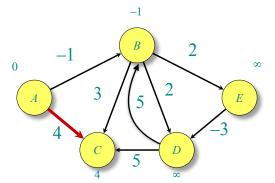
Order of edges: (B,E), (D,B), (B,D), (A,B), (A,C), (D,C), (B,C), (E,D)

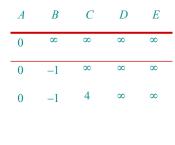


A	В	C	D	E	
0	∞	∞	∞	∞	_
0	-1	$\infty$	$\infty$	$\infty$	

# **Example of Bellman-Ford**

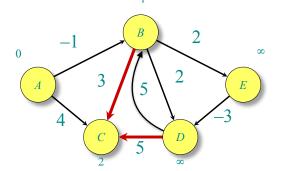
Order of edges: (B,E), (D,B), (B,D), (A,B), (A,C), (D,C), (B,C), (E,D)

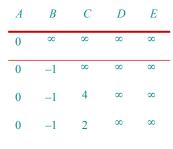




# **Example of Bellman-Ford**

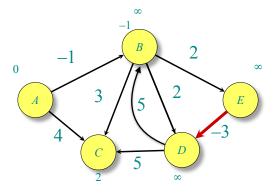
Order of edges: (B,E), (D,B), (B,D), (A,B), (A,C), (D,C), (B,C), (E,D)





## **Example of Bellman-Ford**

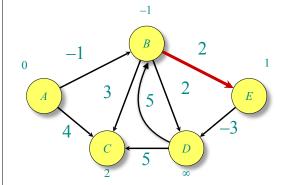
Order of edges: (B,E), (D,B), (B,D), (A,B), (A,C), (D,C), (B,C), (E,D)



A	В	C	D	E
0	∞	∞	∞	∞
0	-1	∞	∞	∞
0	-1	4	∞	∞
0	-1	2	∞	∞

### **Example of Bellman-Ford**

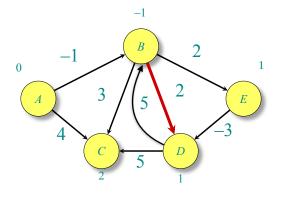
Order of edges: (B,E), (D,B), (B,D), (A,B), (A,C), (D,C), (B,C), (E,D)



A	В	C	D	E
0	∞	∞	∞	∞
0	-1	∞	∞	∞
0	-1	4	∞	∞
0	-1	2	∞	∞
0	-1	2	∞	1

# **Example of Bellman-Ford**

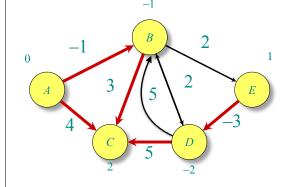
Order of edges: (B,E), (D,B), (B,D), (A,B), (A,C), (D,C), (B,C), (E,D)



A	В	C	D	E
0	∞	∞	∞	∞
0	-1	∞	∞	∞
0	-1	4	∞	∞
0	-1	2	∞	∞
0	-1	2	∞	1
0	-1	2	1	1

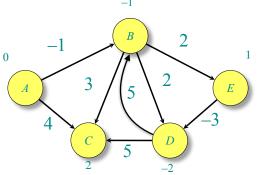
# **Example of Bellman-Ford**

Order of edges: (B,E), (D,B), (B,D), (A,B), (A,C), (D,C), (B,C), (E,D)



A	В	C	D	E
0	∞	∞	∞	∞
0	-1	∞	∞	∞
0	-1	4	∞	∞
0	-1	2	∞	∞
0	-1	2	∞	1
0	-1	2	1	1
0	-1	2	-2	1

## **Example of Bellman-Ford**



**Note:** Values decrease monotonically.

A	В	C	D	E
0	∞	∞	∞	∞
0	-1	∞	∞	∞
0	-1	4	∞	∞
0	-1	2	∞	∞
0	-1	2	∞	1
0	-1	2	1	1
0	-1	2	-2	1

#### Order of edges: (B,E), (D,B), (B,D), (A,B), (A,C), (D,C), (B,C), (E,D)

-1	A	B	C	D	E
B 2	0	∞	∞	∞	∞
	0	-1	∞	∞	∞
$\int \left( 5 \right)^2$	0	-1	4	∞	∞
<del>-3</del>	0	-1	2	∞	∞
5 D	0	-1	2	∞	1
-2	0	-1	2	1	1

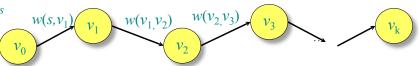
#### **Correctness**

**Recall**  $\delta(s, v)$  is the length of a shortest path from s to v.

**Lemma** If G = (V, E) contains no negative-weight cycles, then during BF-algorithm  $d[v] \ge \delta(s, v)$ , for every vertex v, for all  $v \in V$ .

**Proof Sketch:** d[v] is either  $\infty$ , or is the length of some path  $s \to v$ .  $\delta(s, v)$  is the length of the shortest such path.

# **Correctness (continued)**



- Let p be the shortest path from s to a vertex v. Lets re-label the vertices along p so  $s = v_0$ . The next vertex along this path will be labeled  $v_1$ , the next is  $v_2$  and so on. The new "name" of v is  $v_k$
- Note that any portion of p is also the shortest path to each  $v_i$
- Initially,  $d[v_0] = 0 = \delta(s, v_0)$ , and d[s] is unchanged by subsequent relaxations (note that  $\delta(s, s) \ge 0$ (why?)).
- After 1 pass through E, we have  $d[v_1] = \delta(s, v_1) = w(s, v_1)$ .
- After 2 passes through E, we have  $d[v_2] = d[v_1] + w(v_1, v_2) = w(s, v_1) + w(v_1, v_2) = \delta(s, v_2).$
- After k passes through E, we have  $d[v_k] = \delta(s, v_k)$ .

Since G contains no negative-weight cycles, p is simple. Longest simple path has  $\leq |V| - 1$  edges.

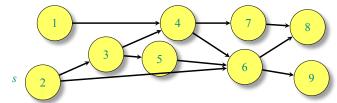
#### **Detection of negative-weight cycles**

**Corollary.** If a value d[v] fails to converge after |V|-1 passes, there exists a negativeweight cycle in G reachable from s.

# **DAG** shortest paths

If the graph is a *directed acyclic graph* (*DAG*), we first *topologically sort* the vertices.

- Determine  $f: V \to \{1, 2, ..., |V|\}$  such that  $(u, v) \in E$  $\Rightarrow f(u) < f(v)$ .
- O(V + E) time using depth-first search.



Walk through the vertices  $u \in V$  in this order, relaxing the edges in Adj[u], thereby obtaining the shortest paths from s in a total of O(V + E) time.