

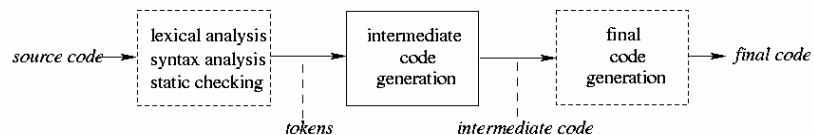
CSc 453

Intermediate Code Generation

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Overview



- Intermediate representations span the gap between the source and target languages:
 - closer to target language;
 - (more or less) machine independent;
 - allows many optimizations to be done in a machine-independent way.
- Implementable via syntax directed translation, so can be folded into the parsing process.

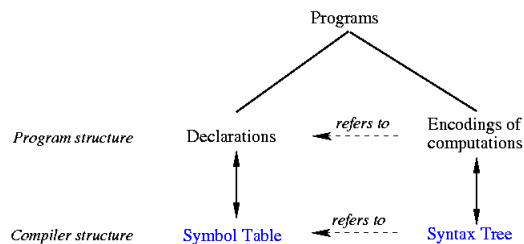
Types of Intermediate Languages

- High Level Representations (e.g., syntax trees):
 - closer to the source language
 - easy to generate from an input program
 - code optimizations may not be straightforward.
- Low Level Representations (e.g., 3-address code, RTL):
 - closer to the target machine;
 - easier for optimizations, final code generation;

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Syntax Trees



A syntax tree shows the structure of a program by abstracting away irrelevant details from a parse tree.

- Each node represents a computation to be performed;
- The children of the node represents what that computation is performed on.

Syntax trees decouple parsing from subsequent processing.

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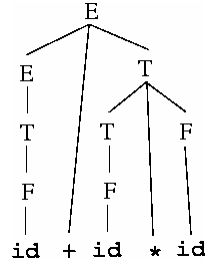
Syntax Trees: Example

Grammar :

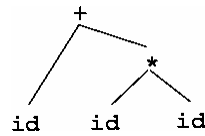
$E \rightarrow E + T \mid T$
 $T \rightarrow T * F \mid F$
 $F \rightarrow (E) \mid \text{id}$

Input: `id + id * id`

Parse tree:



Syntax tree:



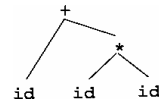
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Syntax Trees: Structure

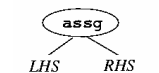
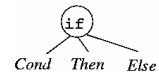
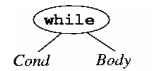
- Expressions:

- leaves: identifiers or constants;
- internal nodes are labeled with operators;
- the children of a node are its operands.



- Statements:

- a node's label indicates what kind of statement it is;
- the children correspond to the components of the statement.



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Constructing Syntax Trees

General Idea: construct bottom-up using synthesized attributes.

$E \rightarrow E + E$ { \$\$ = *mkTree*(PLUS, \$1, \$3); }

$S \rightarrow \text{if } (' E ') S \text{ OptElse}$ { \$\$ = *mkTree*(IF, \$3, \$5, \$6); }

$\text{OptElse} \rightarrow \text{else } S$ { \$\$ = \$2; }
 | /* epsilon */ { \$\$ = NULL; }

$S \rightarrow \text{while } (' E ') S$ { \$\$ = *mkTree*(WHILE, \$3, \$5); }

mkTree(NodeType, Child1, Child2, ...) allocates space for the tree node and fills in its node type as well as its children.

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Three Address Code

- Low-level IR
- instructions are of the form ' $x = y \text{ op } z$,' where x , y , z are variables, constants, or "temporaries".
- At most one operator allowed on RHS, so no 'built-up' expressions.
Instead, expressions are computed using temporaries (compiler-generated variables).

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Three Address Code: Example

- Source:

```
if ( x + y*z > x*y + z )
    a = 0;
```

- Three Address Code:

```
tmp1 = y*z
tmp2 = x+t1          // x + y*z
tmp3 = x*y
tmp4 = t3+z          // x*y + z
if (tmp2 > tmp4) goto L
a = 0
L:
```

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An Intermediate Instruction Set

- Assignment:

- $x = y \text{ op } z$ (op binary)
- $x = \text{op } y$ (op unary);
- $x = y$

- Jumps:

- if ($x \text{ op } y$) goto L (L a label);
- goto L

- Pointer and indexed assignments:

- $x = y[z]$
- $y[z] = x$
- $x = \&y$
- $x = *y$
- $*y = x.$

- Procedure call/return:

- param x, k (x is the k^{th} param)
- retval x
- call p
- enter p
- leave p
- return
- retrieve x

- Type Conversion:

- $x = \text{cvt}_{A \text{ to } B} y$ (A, B base types)
e.g.: $\text{cvt}_{\text{int to float}}$

- Miscellaneous

- label L

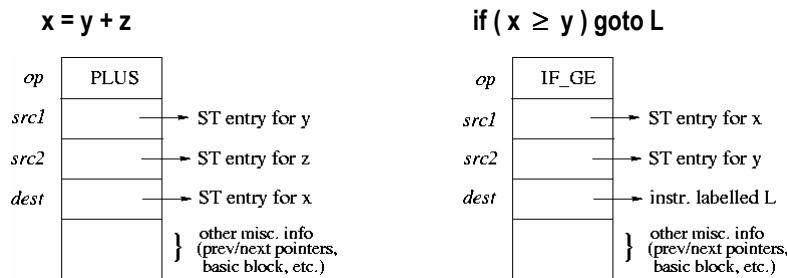
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Three Address Code: Representation

- Each instruction represented as a structure called a *quadruple* (or “*quad*”):
 - contains info about the operation, up to 3 operands.
 - for operands: use a bit to indicate whether constant or ST pointer.

E.g.:



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Code Generation: Approach

- function prototypes, global declarations:
 - save information in the global symbol table.
- function definitions:
 - function name, return type, argument type and number saved in global table (if not already there);
 - process formals, local declarations into local symbol table;
 - process body:
 - construct syntax tree;
 - traverse syntax tree and generate code for the function;
 - deallocate syntax tree and local symbol table.

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Code Generation: Approach

Recursively traverse syntax tree:

- Node type determines action at each node;
- Code for each node is a (doubly linked) list of three-address instructions;
- Generate code for each node after processing its children

```
codeGen_stmt(synTree_node S)      codeGen_expr(synTree_node E)
{                                  {
  switch (S.nodetype) {           switch (E.nodetype) {
    case FOR: ... ; break;        case '+': ... ; break;
    case WHILE: ... ; break;     case '*': ... ; break;
    case IF: ... ; break;        case '-': ... ; break;
    case '=': ... ; break;       case '/': ... ; break;
    ...                           ...
  }                                }
```

*recursively process the children,
then generate code for this node
and glue it all together.*

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Intermediate Code Generation

Auxiliary Routines:

- *struct symtab_entry *newtemp(typename t)*
creates a symbol table entry for new temporary variable each time it is called, and returns a pointer to this ST entry.
- *struct instr *newlabel()*
returns a new label instruction each time it is called.
- *struct instr *newinstr(arg₁, arg₂, ...)*
creates a new instruction, fills it in with the arguments supplied, and returns a pointer to the result.

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Intermediate Code Generation...

- struct symtab_entry *newtemp(t)
{
 struct symtab_entry *ntmp = malloc(...); /* check: ntmp == NULL? */
 ntmp->name = ...create a new name that doesn't conflict...
 ntmp->type = t;
 ntmp->scope = LOCAL;
 return ntmp;
}
- struct instr *newinstr(opType, src1, src2, dest)
{
 struct instr *ninstr = malloc(...); /* check: ninstr == NULL? */
 ninstr->op = opType;
 ninstr->src1 = src1; ninstr->src2 = src2; ninstr->dest = dest;
 return ninstr;
}

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Intermediate Code for a Function

Code generated for a function f :

- begin with 'enter f ', where f is a pointer to the function's symbol table entry:
 - this allocates the function's activation record;
 - activation record size obtained from f 's symbol table information;
- this is followed by code for the function body;
 - generated using `codegen_stmt(...)` [to be discussed soon]
- each return in the body (incl. any implicit return at the end of the function body) are translated to the code

```
leave  $f$  /* clean up:  $f$  a pointer to the function's symbol table entry */  
return /* + associated return value, if any */
```

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Simple Expressions

Syntax tree node for expressions augmented with the following fields:



- type: the type of the expression (or "error");
- code: a list of intermediate code instructions for evaluating the expression.
- place: the location where the value of the expression will be kept at runtime:

Simple Expressions

Syntax tree node for expressions augmented with the following fields:

- type: the type of the expression (or "error");
- code: a list of intermediate code instructions for evaluating the expression.
- place: the location where the value of the expression will be kept at runtime:
 - When generating intermediate code, this just refers to a symbol table entry for a variable or temporary that will hold that value;
 - The variable/temporary is mapped to an actual memory location when going from intermediate to final code.

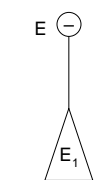
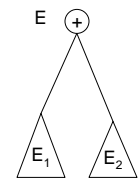
Simple Expressions 1

Syntax tree node E	Action during intermediate code generation
	<pre>codeGen_expr(E) { /* E.nodetype == INTCON; */ E.place = newtemp(E.type); E.code = 'E.place = intcon.val'; }</pre>
	<pre>codeGen_expr(E) { /* E.nodetype == ID; */ /* E.place is just the location of id (nothing more to do) */ E.code = NULL; }</pre>

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Simple Expressions 2

Syntax tree node E	Action during intermediate code generation
	<pre>codeGen_expr(E) { /* E.nodetype == UNARY_MINUS */ codeGen_expr(E1); /* recursively traverse E1, generate code for it */ E.place = newtemp(E.type); /* allocate space to hold E's value */ E.code = E1.code @ newinstr(UMINUS, E1.place, NULL, E.place); }</pre>
	<pre>codeGen_expr(E) { /* E.nodetype == '+' ... other binary operators are similar */ codeGen_expr(E1); codeGen_expr(E2); /* generate code for E1 and E2 */ E.place = newtemp(E.type); /* allocate space to hold E's value */ E.code = E1.code @ E2.code @ newinstr(PLUS, E1.place, E2.place, E.place); }</pre>

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Accessing Array Elements 1

- Given:
 - an array $A[lo\dots hi]$ that starts at address b ;
 - suppose we want to access $A[i]$.
- We can use indexed addressing in the intermediate code for this:
 - $A[i]$ is the $(i + lo)^{\text{th}}$ array element starting from address b .
 - Code generated for $A[i]$ is:

```
t1 = i + lo
t2 = A[ t1 ] /* A being treated as a 0-based array at this level. */
```

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Accessing Array Elements 2

- In general, address computations can't be avoided, due to pointer and record types.
- Accessing $A[i]$ for an array $A[lo\dots hi]$ starting at address b , where each element is w bytes wide:

$$\begin{aligned}\text{Address of } A[i] \text{ is } & b + (i - lo) * w \\ & = (b - lo * w) + i * w \\ & = k_A + i * w.\end{aligned}$$

k_A depends only on A , and is known at compile time.

- Code generated:

```
t1 = i * w
t2 = k_A + t1 /* address of A[i] */
t3 = *t2
```

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Accessing Structure Fields

- Use the symbol table to store information about the order and type of each field within the structure.
 - Hence determine the distance from the start of a struct to each field.
 - For code generation, add the displacement to the base address of the structure to get the address of the field.

- Example: Given

```
struct s { ... } *p;
```

```
...
```

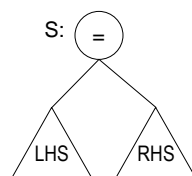
```
x = p->a; /* a is at displacement  $\delta_a$  within struct s */
```

The generated code has the form:

```
t1 = p +  $\delta_a$  /* address of p->a */
```

```
x = *t1
```

Assignments



Code structure:

evaluate LHS

evaluate RHS

copy value of RHS into LHS

```
codeGen_stmt(S):
```

```
/* base case: S.nodetype = 'S' */
```

```
codeGen_expr(LHS);
```

```
codeGen_expr(RHS);
```

```
S.code = LHS.code
```

```
⊕ RHS.code
```

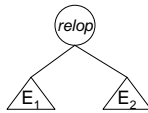
```
⊕ newinstr(ASSG,
```

```
LHS.place,
```

```
RHS.place);
```

Logical Expressions 1

- Syntax tree node:



- Naïve but Simple Code (TRUE=1, FALSE=0):

```
t1 = { evaluate E1
t2 = { evaluate E2
t3 = 1    /* TRUE */
if ( t1 relop t2 ) goto L
t3 = 0    /* FALSE */
```

L: ...

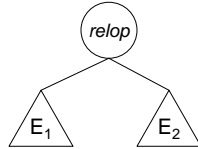
- Disadvantage: lots of unnecessary memory references.

Logical Expressions 2

- Observation: Logical expressions are used mainly to direct flow of control.
- Intuition: “tell” the logical expression where to branch based on its truth value.
 - When generating code for B , use two inherited attributes, $trueDst$ and $falseDst$. Each is (a pointer to) a *label* instruction.
E.g.: for a statement **if** (B) S_1 **else** S_2 :
 $B.trueDst$ = start of S_1
 $B.falseDst$ = start of S_2
 - The code generated for B jumps to the appropriate label.

Logical Expressions 2: cont'd

Syntax tree:



```
codeGen_bool(B, trueDst, falseDst):
/* base case: B.nodetype == relop */
B.code = E1.code
⊕ E2.code
⊕ newinstr(relop, E1.place, E2.place, trueDst)
⊕ newinstr(GOTO, falseDst, NULL, NULL);
```

Example: $B \Rightarrow x+y > 2*z$.

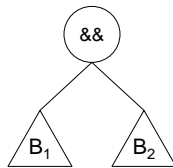
Suppose $trueDst = Lbl1$, $falseDst = Lbl2$.

```
E1 ≡ x+y, E1.place = tmp1, E1.code ≡ < 'tmp1 = x + y' >
E2 ≡ 2*z, E2.place = tmp2, E2.code ≡ < 'tmp2 = 2 * z' >
B.code = E1.code ⊕ E2.code ⊕ 'if (tmp1 > tmp2) goto Lbl1' ⊕ goto Lbl2
= < 'tmp1 = x + y', 'tmp2 = 2 * z', 'if (tmp1 > tmp2) goto Lbl1', goto Lbl2 >
```

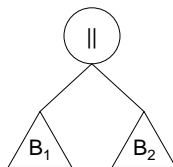
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Short Circuit Evaluation



```
codeGen_bool (B, trueDst, falseDst):
/* recursive case 1: B.nodetype == '&&' */
L1 = newlabel( );
codeGen_bool(B1, L1, falseDst);
codeGen_bool(B2, trueDst, falseDst);
B.code = B1.code ⊕ L1 ⊕ B2.code;
```



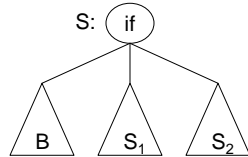
```
codeGen_bool (B, trueDst, falseDst):
/* recursive case 2: B.nodetype == '||' */
L1 = newlabel( );
codeGen_bool(B1, trueDst, L1);
codeGen_bool(B2, trueDst, falseDst);
B.code = B1.code ⊕ L1 ⊕ B2.code;
```

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Conditionals

Syntax Tree:



- Code Structure:**

```

code to evaluate B
L_then: code for S1
    goto L_after
L_else: code for S2
L_after: ...
  
```

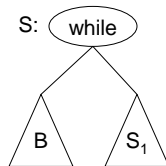
```

codegen_stmt(S):
/* S.nodetype == 'IF' */
L_then = newlabel();
L_else = newlabel();
L_after = newlabel();
codegen_bool(B, L_then, L_else);
codegen_stmt(S1);
codegen_stmt(S2);
S.code = B.code
    ⊕ L_then
    ⊕ S1.code
    ⊕ newinstr(GOTO, L_after)
    ⊕ L_else
    ⊕ S2.code
    ⊕ L_after;
  
```

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Loops 1



Code Structure:

```

L_top: code to evaluate B
    if (!B) goto L_after
L_body: code for S1
    goto L_top
L_after: ...
  
```

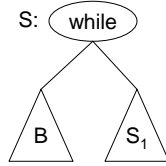
```

codegen_stmt(S):
/* S.nodetype == 'WHILE' */
L_top = newlabel();
L_body = newlabel();
L_after = newlabel();
codegen_bool(B, L_body, L_after);
codegen_stmt(S1);
S.code = L_top
    ⊕ B.code
    ⊕ L_body
    ⊕ S1.code
    ⊕ newinstr(GOTO, L_top)
    ⊕ L_after;
  
```

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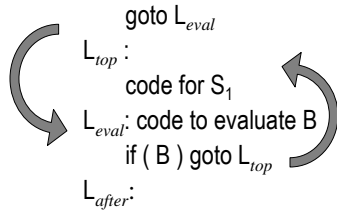
Loops 2



```

codegen_stmt(S):
/* S.nodetype = 'WHILE' */
  L_top = newlabel();
  L_eval = newlabel();
  L_after = newlabel();
  codeGen_bool(B, L_top, L_after);
  codeGen_stmt(S1);
  S.code =
    newinstr(GOTO, L_eval)
    ⊕ L_top
    ⊕ S1.code
    ⊕ L_eval
    ⊕ B.code
    ⊕ L_after ;
  
```

Code Structure:



This code executes fewer branch ops.

Multi-way Branches: switch statements

- **Goal:**
generate code to (efficiently) choose amongst a fixed set of alternatives based on the value of an expression.
- **Implementation Choices:**
 - *linear search*
 - best for a small number of case labels (≈ 3 or 4)
 - cost increases with no. of case labels; later cases more expensive.
 - *binary search*
 - best for a moderate number of case labels ($\approx 4 - 8$)
 - cost increases with no. of case labels.
 - *jump tables*
 - best for large no. of case labels (≥ 8)
 - may take a large amount of space if the labels are not well-clustered.

Background: Jump Tables

- A jump table is an array of code addresses:
 - $Tbl[i]$ is the address of the code to execute if the expression evaluates to i .
 - if the set of case labels have “holes”, the correspond jump table entries point to the default case.
- Bounds checks:
 - Before indexing into a jump table, we must check that the expression value is within the proper bounds (if not, jump to the default case).
 - The check

$$lower_bound \leq exp_value \leq upper\ bound$$
 can be implemented using a single unsigned comparison.

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Jump Tables: cont'd

- Given a **switch** with max. and min. case labels c_{max} and c_{min} , the jump table is accessed as follows:

<u>Instruction</u>	<u>Cost</u> (cycles)
$t_0 \leftarrow$ value of expression	...
$t_0 = t_0 - c_{min}$	1
if $\neg(t_0 \leq_u c_{max} - c_{min})$ goto <i>DefaultCase</i>	4 to 6
$t_1 = \text{JmpTbl_BaseAddr}$	1
$t_1 += 4 * t_0$	1
jmp *t1	3 to 5

Σ : 10 to 14

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Jump Tables: Space Costs

- A jump table with max. and min. case labels c_{max} and c_{min} needs $\approx c_{max} - c_{min}$ entries.

This can be wasteful if the entries aren't "dense enough", e.g.:

```
switch (x) {  
  case 1: ...  
  case 1000: ...  
  case 1000000: ...  
}
```

- Define the *density* of a set of case labels as
density = no. of case labels / $(c_{max} - c_{min})$
- Compilers will not generate a jump table if density below some threshold (typically, 0.5).

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Switch Statements: Overall Algorithm

- if no. of case labels is small ($\leq \sim 8$), use linear or binary search.
 - use no. of case labels to decide between the two.
- if density \geq threshold (~ 0.5) :
 - generate a jump table;
- else :
 - divide the set of case labels into sub-ranges s.t. each sub-range has density \geq threshold;
 - generate code to use binary search to choose amongst the sub-ranges;
 - handle each sub-range recursively.

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Function Calls

- Caller:
 - evaluate actual parameters, place them where the callee expects them:
 - param x, k /* x is the kth actual parameter of the call */
 - save appropriate machine state (e.g., return address) and transfer control to the callee:
 - call p
- Callee:
 - allocate space for activation record, save callee-saved registers as needed, update stack/frame pointers:
 - enter p

Function Returns

- Callee:
 - restore callee-saved registers; place return value (if any) where caller can find it; update stack/frame pointers:
 - retval x;
 - leave p
 - transfer control back to caller:
 - return
- Caller:
 - save value returned by callee (if any) into x:
 - retrieve x

Function Call/Return: Example

- Source: $x = f(0, y+1) + 1$;
- Intermediate Code: Caller:


```
t1 = y+1
param t1, 2
param 0, 1
call f
retrieve t2
x = t2+1
```
- Intermediate Code: Callee:

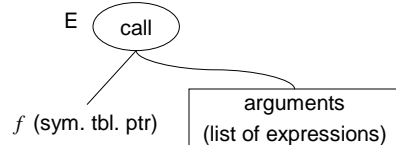

```
enter f      /* set up activation record */
...         /* code for f's body */
retval t27  /* return the value of t27 */
leave f     /* clean up activation record */
return
```

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Intermediate Code for Function Calls

- non-void return type:



Code Structure:

```
... evaluate actuals ...
param xk }
...      } R-to-L
param x1 }
call f
retrieve t0 /* t0 a temporary var */
```

codegen_expr(E):

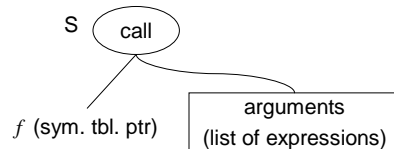
```
/* E.nodetype = FUNCALL */
codegen_expr_list(arguments);
E.place = newtemp( f.returnType );
E.code = ...code to evaluate the arguments...
⊕ param xk
...
⊕ param x1
⊕ call f, k
⊕ retrieve E.place;
```

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Intermediate Code for Function Calls

- void return type:



Code Structure:

... evaluate actuals ...

param x_k
...
param x_1 } R-to-L

call f

~~retrieve t0 /* t0 a temporary var */~~

codegen_stmt(S):

/* S.nodetype = FUNCALL */

codegen_expr_list(arguments);

~~E.place = newtemp(f.returnType);~~

S.code = ...code to evaluate the arguments...

⊕ param x_k

...

⊕ param x_1

⊕ call f, k

~~⊕ retrieve E.place;~~

void return type \Rightarrow f has no return value
 \Rightarrow no need to allocate space for one, or
to retrieve any return value.

Reusing Temporaries

Storage usage can be reduced considerably by reusing space for temporaries:

- For each type T , keep a “free list” of temporaries of type T ;
- $newtemp(T)$ first checks the appropriate free list to see if it can reuse any temps; allocates new storage if not.
- putting temps on the free list:
 - distinguish between user variables (not freed) and compiler-generated temps (freed);
 - free a temp after the point of its last use (i.e., when its value is no longer needed).