

# CSc 453

## Interpreters & Interpretation

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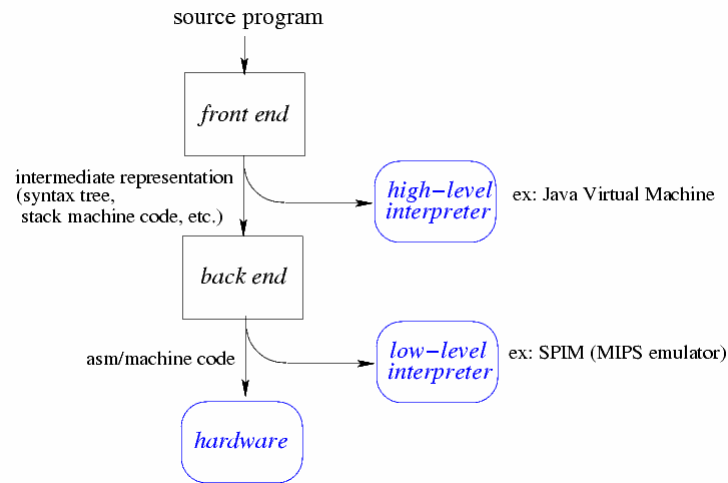
## Interpreters



An *interpreter* is a program that executes another program.

- An interpreter implements a *virtual machine*, which may be different from the underlying hardware platform.  
Examples: Java Virtual Machine; VMs for high-level languages such as Scheme, Prolog, Icon, Smalltalk, Perl, Tcl.
- The virtual machine is often at a higher level of semantic abstraction than the native hardware.
  - This can help portability, but affects performance.

## Interpretation vs. Compilation



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## Interpreter Operation



```
ip = start of program;  
while (  $\neg$  done ) {  
    op = current operation at ip;  
    execute code for op on current operands;  
    advance ip to next operation;  
}
```

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## Interpreter Design Issues



- Encoding the operation
  - I.e., getting from the opcode to the code for that operation (“dispatch”):
    - byte code (e.g., JVM)
    - indirect threaded code
    - direct threaded code.
- Representing operands
  - register machines: operations are performed on a fixed finite set of global locations (“registers”) (e.g.: SPIM);
  - stack machines: operations are performed on the top of a stack of operands (e.g.: JVM).

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## Byte Code



- Operations encoded as small integers (~1 byte).
- The interpreter uses the opcode to index into a table of code addresses:

```
while ( TRUE ) {  
    byte op = *ip;  
    switch ( op ) {  
        case ADD: ... perform addition; break;  
        case SUB: ... perform subtraction; break;  
        ...  
    }  
}
```

- Advantages: simple, portable.
- Disadvantages: inefficient.

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## Direct Threaded Code

- Indexing through a jump table (as with byte code) is expensive.
- Idea: Use the address of the code for an operation as the opcode for that operation.
  - *The opcode may no longer fit in a byte.*

```
while ( TRUE ) {  
    addr op = *ip;  
    goto *op; /* jump to code for the operation */  
}
```

- More efficient, but the interpreted code is less portable.

[James R. Bell. Threaded Code. *Communications of the ACM*, vol. 16 no. 6, June 1973, pp. 370–372]

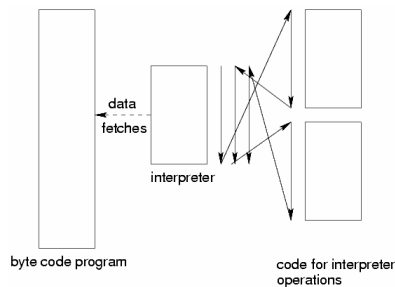


## Byte Code vs. Threaded Code

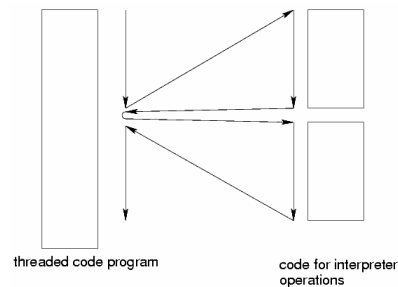
### Control flow behavior:

[based on: James R. Bell. Threaded Code. *Communications of the ACM*, vol. 16 no. 6, June 1973, pp. 370–372]

byte code:



threaded code:





## Indirect Threaded Code

- Intermediate in portability, efficiency between byte code and direct threaded code.
- Each opcode is the address of a word that contains the address of the code for the operation.
  - *Avoids some of the costs associated with translating a jump table index into a code address.*

```
while ( TRUE ) {
  addr op = *ip;
  goto **op; /* jump to code for the operation */
}
```

[R. B. K. Dewar. Indirect Threaded Code. *Communications of the ACM*, vol. 18 no. 6, June 1975, pp. 330-331]



## Example

### program operations

add  
mul  
sub  
mul  
add

### memory address

10000  
11000  
12000  
13000  
...

### operation

add: ...
sub: ...
mul: ...
div: ...

<u>byte code</u>	<u>Op Table</u>	
	<u>index</u>	<u>contents</u>
17	17	10000
23	18	11000
23	23	12000
17	27	13000

<u>direct threaded</u>
10000
12000
11000
12000
10000

<u>indirect threaded</u>	<u>Op Table</u>	
	<u>addr</u>	<u>contents</u>
6000	6000	10000
6008	6004	11000
6008	6008	12000
6000	6012	13000

## Handling Operands 1: Stack Machines



- Used by Pascal interpreters ('70s and '80s); resurrected in the Java Virtual Machine.
- Basic idea:
  - operands and results are maintained on a stack;
  - operations pop operands off this stack, push the result back on the stack.
- Advantages:
  - simplicity
  - compact code.
- Disadvantages:
  - code optimization (e.g., utilizing hardware registers effectively) not easy.

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## Stack Machine Code



- The code for an operation ' $op\ x_1, \dots, x_n$ ' is:

```
push  $x_n$ 
...
push  $x_1$ 
op
```
- Example: JVM code for ' $x = 2*y - 1$ ':

```
iconst 1    /* push the integer constant 1 */
iload y     /* push the value of the integer variable y */
iconst 2
imul        /* after this, stack contains: <(2*y), 1> */
isub
istore x    /* pop stack top, store to integer variable x */
```

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## Generating Stack Machine Code



Essentially just a post-order traversal of the syntax tree:

```
void gencode(struct syntaxTreeNode *tnode )
{
    if ( !isLeaf( tnode ) ) { ... }
    else {
        n = tnode->n_operands;
        for ( i = n; i > 0; i-- ) {
            gencode( tnode->operand[i] );    /* traverse children first */
        } /* for */
        gen_instr( opcode_table[tnode->op] ); /* then generate code for the node */
    } /* if [else] */
}
```

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## Handling Operands 2: Register Machines



- Basic idea:
  - Have a fixed set of “virtual machine registers;”
  - Some of these get mapped to hardware registers.
- Advantages:
  - potentially better optimization opportunities.
- Disadvantages:
  - code is less compact;
  - interpreter becomes more complex (e.g., to decode VM register names).

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## Just-in-Time Compilers (JITs)



- Basic idea: compile byte code to native code during execution.
- Advantages:
  - original (interpreted) program remains portable, compact;
  - the executing program runs faster.
- Disadvantages:
  - more complex runtime system;
  - performance may degrade if runtime compilation cost exceeds savings.

## Improving JIT Effectiveness



- Reducing Costs:
  - incur compilation cost only when justifiable;
  - invoke JIT compiler on a per-method basis, at the point when a method is invoked.
- Improving benefits:
  - some systems monitor the executing code;
  - methods that are executed repeatedly get optimized further.



## Method Dispatch: vtables



- vtables (“virtual tables”) are a common implementation mechanism for virtual methods in OO languages.
- The implementation of each class contains a vtable for its methods:
  - each virtual method  $f$  in the class has an entry in the vtable that gives  $f$ 's address.
  - each instance of an object gets a pointer to the corresponding vtable.
  - to invoke a (virtual) method, get its address from the vtable.

## VMs with JITs



- Each method has vtable entries for:
  - byte code address;
  - native code address.
- Initially, the *native code address* field points to the JIT compiler.
- When a method is first invoked, this automatically calls the JIT compiler.
- The JIT compiler:
  - generates native code from the byte code for the method;
  - patches the *native code address* of the method to point to the newly generated native code (so subsequent calls go directly to native code);
  - jumps to the native code.

## JITs: Deciding what to Compile



- For a JIT to improve performance, the benefit of compiling to native code must offset the cost of doing so.

*E.g., JIT compiling infrequently called straight-line code methods can lead to a slowdown!*

- We want to JIT-compile only those methods that contain frequently executed (“hot”) code:
  - methods that are called a large number of times; or
  - methods containing loops with large iteration counts.

## JITs: Deciding what to Compile



- Identifying frequently called methods:
  - count the number of times each method is invoked;
  - if the count exceeds a threshold, invoke JIT compiler.
  - (In practice, start the count at the threshold value and count down to 0: this is slightly more efficient.)
- Identifying hot loops:
  - modify the interpreter to “snoop” the loop iteration count when it finds a loop, using simple bytecode pattern matching.
  - use the iteration count to adjust the amount by which the invocation count for the method is decremented on each call.

## Typical JIT Optimizations



Choose optimizations that are cheap to perform and likely to improve performance, e.g.:

- inlining frequently called methods:  
*consider both code size and call frequency in inlining decision.*
- exception check elimination:  
*eliminate redundant null pointer checks, array bounds checks.*
- common subexpression elimination:  
*avoid address recomputation, reduce the overhead of array and instance variable access.*
- simple, fast register allocation.