

# CSc 520

## Principles of Programming Languages

### 14 : Types — Classification

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## Enumerable Types

- Also called **discrete types** or **ordinal** types.
- Discrete types are countable, or 1-to-1 with the integers.
- Examples:
  1. **integer**
  2. **boolean**
  3. **char**
  4. **subranges**
  5. **enumeration types**

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## Scalar Types

- Also called **simple** types.
- The scalar types include:
  1. **discrete types**
  2. **real**
  3. **rational**
  4. **complex**

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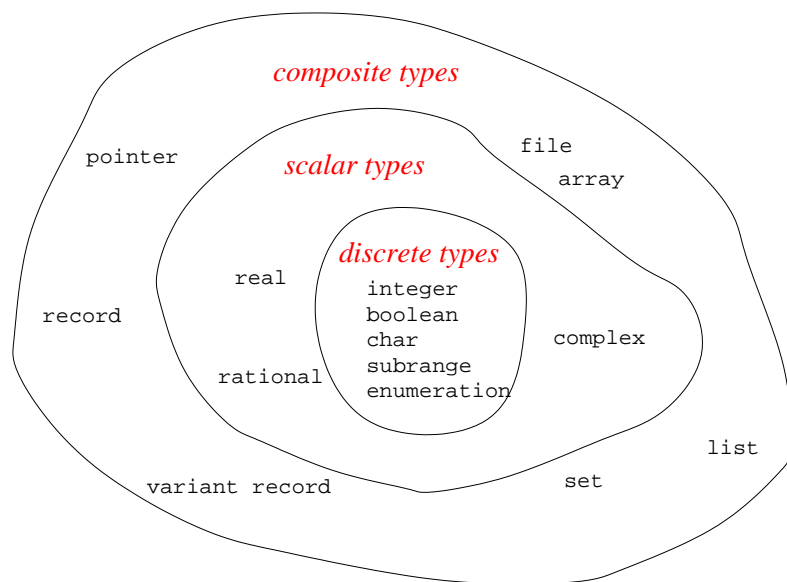
## Composite Types

- Also called **constructed** types.
- They are created by applying **type constructors** to other, simpler, types.
- The composite types include:
  1. **records**
  2. **variant records**
  3. **arrays**
  4. **sets**
  5. **pointers**
  6. **lists**
  7. **files**

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# Types — Overview



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# Discreet Types — Enumerations

- Pascal, Ada, Modula-2, C have some variant of enumeration types.
- C's enumerations are just syntactic sugar for integer constants.
- In Pascal and Ada, enumerations are real types, incompatible with other types.
- In Ada and C, enumeration values can be user specified.

```
TYPE Color = (white,blue,yellow,green,red);  
TYPE Fruits = (apple=4,pear=9,kumquat=99);  
VAR A : ARRAY Color OF Fruit;  
FOR c := white TO red DO  
    IF c != yellow THEN A[c] := apple;
```

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## Discreet Types — Subranges

- Subranges can be used to force additional runtime checks.
- Some languages use subrange types as array index types.

```
TYPE S1 = [0..10];  
TYPE S2 = ['a'..'z'];  
TYPE Color = (white,blue,yellow,green,red);  
TYPE S3 = [blue..green];  
TYPE A = ARRAY S3 OF INTEGER;  
VAR X : S3 := white; (* ← error *)
```

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## Structured Types

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# Arrays – Storage Layout

- Most languages lay out arrays in row-major order. FORTRAN uses column-major.

A[1,1]	A[1,2]
A[2,1]	A[2,2]
A[3,1]	A[3,2]
A[4,1]	A[4,2]

Matrix

0	A[1,1]
1	A[1,2]
2	A[2,1]
3	A[2,2]
4	A[3,1]
5	A[3,2]
6	A[4,1]
7	A[4,2]

Row Major

0	A[1,1]
1	A[2,1]
2	A[3,1]
3	A[4,1]
4	A[1,2]
5	A[2,2]
6	A[3,2]
7	A[4,2]

Column Major

# Array Indexing – 1 Dimensions

- How do we compute the address ( $L$ -value) of the  $n$ :th element of a 1-dimensional array?
- $A_{\text{elsz}}$  is  $A$ 's element-size,  $A_{\text{addr}}$  is its base address.

**VAR A : ARRAY [1 .. h] OF T;**

$$\begin{aligned}
 L - \text{VAL}(A[i]) &\equiv A_{\text{addr}} + (i - l) * A_{\text{elsz}} \\
 &\equiv A_{\text{addr}} + (l * A_{\text{elsz}}) + i * A_{\text{elsz}} \\
 C &\equiv A_{\text{addr}} + (l * A_{\text{elsz}}) \\
 L - \text{VAL}(A[i]) &\equiv C + i * A_{\text{elsz}}
 \end{aligned}$$

- Note that  $C$  can be computed at compile-time.

# Array Indexing – 2 Dimensions

**VAR A : ARRAY [l<sub>1</sub> .. h<sub>1</sub>] [l<sub>2</sub> .. h<sub>2</sub>] OF T;**

$$\begin{aligned}
 w_1 &\equiv h_1 - l_1 + 1 \\
 w_2 &\equiv h_2 - l_2 + 1 \\
 L - \text{VAL}(A[i_1, i_2]) &\equiv A_{\text{addr}} + ((i_1 - l_1) * w_2 + i_2 + l_2) * A_{\text{elsz}} \\
 &\equiv A_{\text{addr}} + (i_1 * w_2 + i_2) * A_{\text{elsz}} - \\
 &\quad (l_1 * w_2 - l_2) * A_{\text{elsz}} \\
 C &\equiv A_{\text{addr}} - (l_1 * w_2 - l_2) * A_{\text{elsz}} \\
 L - \text{VAL}(A[i_1, i_2]) &\equiv (i_1 * w_2 + i_2) * A_{\text{elsz}} + C
 \end{aligned}$$

- $C$  can be computed at compile-time.

# Array Indexing – $n$ Dimensions

**VAR A : ARRAY [l<sub>1</sub> .. h<sub>1</sub>] ... [l<sub>n</sub> .. h<sub>n</sub>] OF T;**

$$w_k \equiv h_k - l_k + 1$$

$$\begin{aligned}
 C &\equiv \\
 &\quad A_{\text{addr}} - ((\dots (l_1 * w_2 + l_2) * w_3 + l_3) \dots) * w_n + l_n) * A_{\text{elsz}}
 \end{aligned}$$

$$\begin{aligned}
 L - \text{VAL}(A[i_1, i_2, \dots, i_n]) &\equiv \\
 &\quad ((\dots (i_1 * w_2 + i_2) * w_3 + i_3) \dots) * w_n + i_n) * A_{\text{elsz}} + C
 \end{aligned}$$

## Record Types

- Pascal, C, Modula-2, Ada and other languages have **variant records** (C's **union** type):

```
TYPE R1 = RECORD tag : (red,blue,green);
CASE tag OF
    red : r : REAL; |
    blue : i : INTEGER; |
    ELSE c : CHAR;
END;
END;
```

Depending on the `tag` value `R1` has a real, integer, or char field.

- The size of a variant part is the max of the sizes of its constituent fields.

## Record Types...

- Oberon has **extensible** record types:

```
TYPE R3 = RECORD
    a : INTEGER;
END;
TYPE R4 = (R3) RECORD
    b : REAL;
END;
```

`R4` has both the `a` and the `b` field.

- Extensible records are similar to classes in other languages.

## Pointer Types

- In order to build recursive structures, most languages allow some way of declaring **recursive types**. These are necessary in order to construct linked structures such as lists and trees:

```
TYPE P = POINTER TO R;
TYPE R = RECORD
    data : INTEGER;
    next : P;
END;
```

- Note that `P` is declared before its use. Languages such as Pascal and C don't allow forward declarations, but make an exception for pointers.

## Procedure Types

- C, Modula-2, and other languages support **procedure types**. You can treat the address of a procedure like any other object.
- Languages differ in whether they allow procedures whose address is taken to be nested or not. (Why?)

```
TYPE P = PROCEDURE(x:INTEGER; VAR Y:CHAR):REAL;
VAR z : P; VAR c : CHAR; VAR r : REAL;
PROCEDURE M (x:INTEGER; VAR Y:CHAR):REAL;
    BEGIN...END;
BEGIN
    z := M; /* z holds the address of M. */
    r := z(44,c);
END.
```

# Class Types

- Java's classes are just pointer to record types. Some languages (Object Pascal, Oberon, MODULA-3) define classes just like records.
- Nore about classes later.

```
TYPE C1 = CLASS
    x : INTEGER;
    void M() { ... };
    void N() { ... };
END;
TYPE C2 = CLASS EXTENDS C1
    r : REAL; // Add another field.
    void M() { ... }; // Overrides C1.M
    void Q() { ... }; // Add another method.
END;
```

# Set Types

- Pascal and Modula-2 support sets of ordinal types.
- Sets are implemented as bitvectors.
- Many implementations restrict the size of a set to 32 (the size of a machine word), or 256 (so you can declare a set of char).

```
type letset = set of 'A' .. 'z';
var x, y, z, w: letset;
begin
    x := ['A'..'Z','a']; y := ['a'..'z'];
    z := x + y; (* set union *)
    z := x * y; (* set intersection *)
    w := x - y; (* set difference *)
    if 'A' in z then ...; (* set membership *)
end.
```

# Readings and References

- Read Scott, pp. 312-320,336-361.