

VARIATIONAL LOWER BOUND

⇒ Consider observed RV  $\mathbf{X} = \mathbf{x}$  w/ marginal likelihood:

$$\begin{aligned}\log P(\mathbf{x}) &= \log \int p(\mathbf{x}, \boldsymbol{\theta}) d\boldsymbol{\theta} \\ &= \log \int q(\boldsymbol{\theta}) \frac{p(\mathbf{x}, \boldsymbol{\theta})}{q(\boldsymbol{\theta})} d\boldsymbol{\theta} \\ &= \log E_q \left[ \frac{p(\mathbf{x}, \boldsymbol{\theta})}{q(\boldsymbol{\theta})} \right] \\ &\geq E_q \left[ \log \frac{p(\mathbf{x}, \boldsymbol{\theta})}{q(\boldsymbol{\theta})} \right] \quad (\text{Jensen's inequality}) \\ &= -\text{KL}(q \parallel p(\mathbf{x}, \boldsymbol{\theta}))\end{aligned}$$

TALK: Fri, 1-2pm,  
EUR2 5316.  
"PROB. REASONING IN  
COMPLEX SYSTEMS: ALG. & APP"

⇒ Variational optimization finds tightest lower bound:

$$\log P(\mathbf{x}) \geq \max_{q \in \mathcal{Q}} -\text{KL}(q(\boldsymbol{\theta}) \parallel p(\mathbf{x}, \boldsymbol{\theta}))$$

for some class of dist'ns  $\mathcal{Q}$

- Bound is tight iff  $q(\boldsymbol{\theta}) = p(\boldsymbol{\theta} | \mathbf{x})$
- KEY IDEA: VI turns statistical inference into optimization

⇒ Different VI methods amount to different  $\mathcal{Q}$

- $\xrightarrow{\text{today's focus}}$  Mean Field =  $\mathcal{Q}^{\text{MF}}$  marginal posterior independence
- Belief Propagation =  $\mathcal{Q}^{\text{BP}}$  "Tree-like" posterior
- Expectation Propagation =  $\mathcal{Q}^{\text{EP}}$  "Tree-Like" in moments

⇒ ASIDE: Info-Theoretic interpretation suggests we should minimize

$$\min_q \text{KL}(q(\boldsymbol{\theta} | \mathbf{x}) \parallel q(\boldsymbol{\theta})) = E_{q(\boldsymbol{\theta} | \mathbf{x})} \left[ \log \frac{p(\boldsymbol{\theta} | \mathbf{x})}{q(\boldsymbol{\theta})} \right]$$

Can't compute this

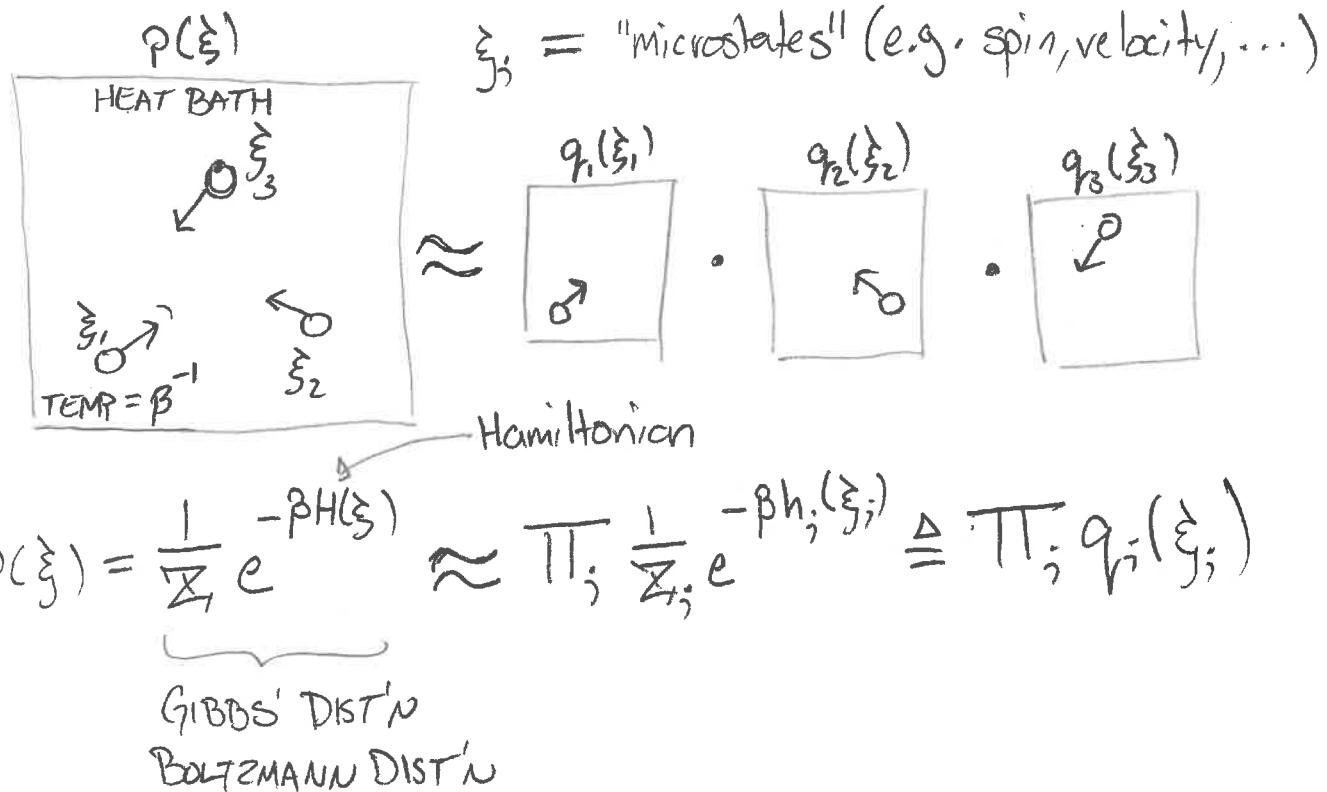
Dont have this ①

## MEAN FIELD VARIATIONAL

⇒ "Mean field" assumes d-dimensional  $\theta$ , marginally independent.

$$q(\theta) = \prod_{i=1}^d q_i(\theta_i)$$

⇒ Originates from many-body problem in stat. mechanics:



⇒ Mean field variational lower bound:

$$\log P(x) \geq \max_q \mathbb{E}_q [\log p(\theta, x)] + \sum_i H(q_i) \triangleq \mathcal{L}(q)$$

- Sometimes called "Evidence Lower Bound" (ELBO)

⇒ How do we optimize  $\mathcal{L}(q)$ ? Coordinate ascent.

- Take derivative wrt each  $q_i(\theta_i)$ , set to 0, solve:

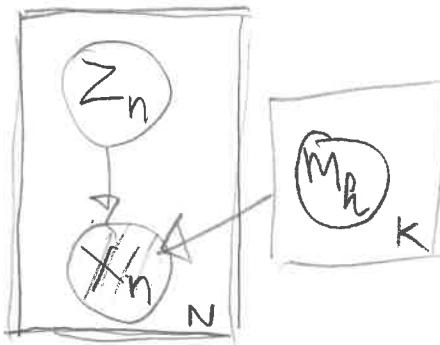
$$q_i^*(\theta_i) \propto \exp \left\{ \mathbb{E}_{q_{\bar{i}}} \left[ \underbrace{\log p(\theta_i | \theta_{\bar{i}}, x)}_{\gamma_i} \right] \right\} \quad (*)$$

where  $\gamma_i = \{1, \dots, d\} \setminus i$  Known as "COMPLETE CONDITIONAL"

## COORDINATE ASCENT VI:

- ⇒ Monotonically increases  $L(\boldsymbol{\gamma})$
- ⇒ Fixed-points of (\*)  $\Leftrightarrow$  Local Optima of  $L(\boldsymbol{\gamma})$

### Ex. GAUSSIAN MIXTURE MODEL



$$m_h \sim N(0, \sigma^2) \quad \text{for } h=1, \dots, K$$

$$z_n \sim \text{CAT}(\frac{1}{K}, \dots, \frac{1}{K}) \quad \text{for } n=1, \dots, N$$

$$x_n | m_{z_n} \sim N(m_{z_n}, 1) \quad \dots$$

- Variational distributions:

$$q_n(z_n | \pi_n) = \text{CAT}(z_n | \pi_n), \quad q_n(m_h | \mu_h, s_h) = N(m_h | \mu_h, s_h)$$

where  $\{\pi_n, \mu_h, s_h\}$  are variational parameters

### ① Update Cluster assignments:

$$q_n(z_n | \pi_n) \propto \exp \left\{ \underbrace{\log p(z_n)}_{\text{PRIOR} = \frac{1}{K}} + \underbrace{\mathbb{E}_{q(m| \mu, s)} [\log p(x_n | z_n, m)]}_{\text{EXPECTED LOG-LIKELIHOOD}} \right\} \quad (\ast\ast)$$

- Compute expected log-likelihood:

$$\begin{aligned} \mathbb{E}_{q(m)} [\log p(x_n | z_n, m)] &= \mathbb{E} \left[ \sum_h \mathbb{I}(z_n=h) \log N(x_n | m_h, 1) \right] \\ &= \sum_h \mathbb{I}(z_n=h) \mathbb{E} \left[ -\frac{1}{2} \log 2\pi 1 - \frac{1}{2} x_n^2 + \cancel{x_n m_h} - \cancel{\frac{1}{2} m_h^2} \right] \\ &= \sum_h \mathbb{I}(z_n=h) \left( \underbrace{\mathbb{E}_{q(m_h)} [m_h]}_{\text{Const.}} x_n - \frac{1}{2} \underbrace{\mathbb{E}_{q(m_h)} [m_h^2]}_{\text{Const.}} \right) + \text{Const.} \end{aligned}$$

- Plug back into (\*\*)

$$q_n(z_n=h) = \pi_n(h) \propto \exp \left\{ \cancel{\mu_h x_n} - \frac{1}{2} (s_n + \mu_h^2) \right\}$$

### ② Update component means $q(m_h | \mu_h, s_h)$ (we will skip that)

(3)

## CONDITIONALLY CONJUGATE MODELS

⇒ In the GMM example our update was:

$$q_n(z_n) \propto p(z_n) \exp\{\mathbb{E}[\log p(x_n | z_n, m)]\} \propto \text{CAT}(\cdot)$$

Which is same family as prior  $p(z_n)$

- We call this conditional conjugacy

⇒ In general this holds when:

1) Complete conditionals are expfam

$$\begin{aligned} 2) q(\theta) &\propto p(\theta) \exp\{\mathbb{E}_z[\log p(x, z | \theta)]\} \\ &= p(\theta) f(x | \theta) \end{aligned}$$

Is conjugate  $\Rightarrow$  Lies in same family as  $p(\theta)$

⇒ Conditional conjugacy  $\Rightarrow$  Closed-form updates

## VARIATIONAL OPTIMIZATION

⇒ How did we get fixed-point condition?

$$q_i(\theta_i) \propto \exp\{\mathbb{E}[ \log p(\theta_i | \theta_{-i}, x) ]\}$$

⇒ Form Lagrangian of variational problem:

$$\max_{q_i} \mathcal{L}(q) \triangleq \mathbb{E}_q[\log p(x, \theta)] + \sum_i H[q_i(\theta_i)]$$

$$\text{s.t. } \int q_i(\theta_i) = 1 \quad \forall i=1, \dots, n$$

Lagrangian:

$$\mathcal{L}(q) + \sum_i \lambda_i (1 - \int q_i(\theta_i) d\theta_i) \triangleq J(q, \lambda)$$

⇒ Calculus of variations defines derivative of functional

$$J(f) = \int L(f(x)) dx$$

AS:

$$\frac{\partial J}{\partial f(x)} = \frac{\partial L}{\partial f}$$

NOTE: This is a simplification of a functional and the Euler-Lagrange equations.

$\Rightarrow$  Take functional derivative wrt  $q_j(\theta_j)$ :

$$\frac{\partial}{\partial q_j(\theta_j)} \mathcal{L}(q) + \frac{\partial}{\partial q_j(\theta_j)} \lambda_j (1 - \int q_j(\theta_j) d\theta_j)$$

$$= \frac{\partial}{\partial q_j(\theta_j)} \mathbb{E}_{q_j} [\mathbb{E}_{q_{-j}} [\log p(\theta_j | \theta_{-j}, x)]]$$
$$+ \frac{\partial}{\partial q_j(\theta_j)} H(q_j(\theta_j)) - \lambda_j$$

$$= \mathbb{E}_{q_j} [\log p(\theta_j | \theta_{-j}, x)] - \log q_j(\theta_j) - 1 - \lambda_j = 0 \Rightarrow$$

$$q_j^*(\theta_j) = \exp \left\{ \mathbb{E}_{q_j} [\log p(\theta_j | \theta_{-j}, x)] \right\} \div \sum_i (\lambda_i)$$

## BETHE VARIATIONAL PROBLEM:

⇒ KEY IDEA: Optimize over dist'n  $q \in \mathcal{Q}^{\text{BETHE}}$  consistent w/ tree-structured MRFs.

⇒ Any tree-structured dist'n  $q(\theta)$  can be written as:

$$q_t(\theta) = \prod_{s \in v} q_s(\theta_s) \prod_{(s,t) \in E} \frac{q_{st}(\theta_s, \theta_t)}{q_s(\theta_s) q_t(\theta_t)} \quad (*)$$

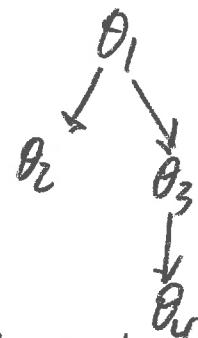
where  $q_s(\theta_s)$  are marginals:

$$q_s(\theta_s) = \int q(\theta_s) d\theta_s$$

Ex

$$q(\theta) = (q_1(\theta_1) q_2(\theta_2) q_3(\theta_3) q_4(\theta_4)) \left( \frac{q_{12}(\theta_1, \theta_2)}{q_1(\theta_1) q_2(\theta_2)} \right) \left( \frac{q_{13}(\theta_1, \theta_3)}{q_1(\theta_1) q_3(\theta_3)} \right) \left( \frac{q_{34}(\theta_3, \theta_4)}{q_3(\theta_3) q_4(\theta_4)} \right).$$

$$= q_1(\theta_1) q_{2|1}(\theta_2|\theta_1) q_{3|1}(\theta_3|\theta_1) q_{4|3}(\theta_4|\theta_3)$$



⇒ Dist'n of the form (\*) necessarily satisfy Local Marginal Consistency:

$$q_s(\theta_s) = \int q_{st}(\theta_s, \theta_t) d\theta_t \quad \forall t \in \Gamma(s) \xrightarrow{\text{Neighbors of } s}$$

⇒ Bethe Variational Problem:

$$\max_q \mathbb{E}_q [\log p(\theta, x)] + H(q)$$

s.t.

$$\int q_{st}(\theta_s, \theta_t) d\theta_t = q_s(\theta_s) \quad \forall t \in \Gamma(s) \quad (\text{Local Consistency})$$

$$\int q_s(\theta_s) d\theta_s = 1 \quad \forall s \in v \quad (\text{Normalization})$$